

6.8

Proportional directional valves

Type 4WRA and 4WRAE

NG 6 and 10 Up to 315 bar Up to 75 L/min



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Features

- Direct operated proportional directional valve to control the direction and magnitude of a flow
- For subplate mounting: Porting pattern conforms to ISO4401
- Actuation by means of proportional solenoids with central thread and removable coil
- Spring centred control spool
- Control electronics 4WRAE...L2X: integrated electronics (OBE) with voltage input or current input (A1 resp. F1)
 4WRA...L2X: available module amplifier

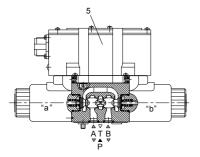
Function and configurations

The 4/2- and 4/3-way proportioanl directional valves are designed as direct operated components for subplate mounting. They are actuated by means of proportional solenoids with central thread and removable coil. The solenoids are controlled either by external control electronics (type 4WRA...L2X) or by integrated control electronics (type 4WRAE...L2X).

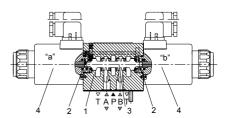
The valves basically consist of: Body (1) with mounting surface, Control spool (3) with compression springs (2), Solenoids (4) with central thread, Optional integrated electronics (5).

With the solenoids (4), de-energised, the control spool (3) is held in the central position by the compression springs (2).

Direct operation of the control spool (3) by energising one of the proportional solenoids(4) e.g. control of solenoid right, then movement of the control spool (3) to the left in proportion to the electrical input signal, and connection from P to A and B to T via orifice-like crosssections with progressive flow characteristics.

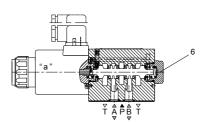


Type 4WRAE 6...-L2X/...

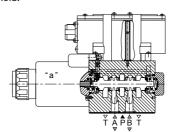


Type 4WRA 10...-L2X/...

4WRA(E)...A-L2X the 2 switched position valves are however only fitted with solenoid "a". A plug (6) is fitted in place on the "b" proportional solenoid.



Type 4WRA 10...A-L2X/...



Type 4WRAE 10...A-L2X/...

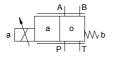
Symbols

Without integrated electronics

Type 4WRA...-L2X/...



Type 4WRA...A-L2X/...

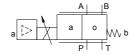


With integrated electronics

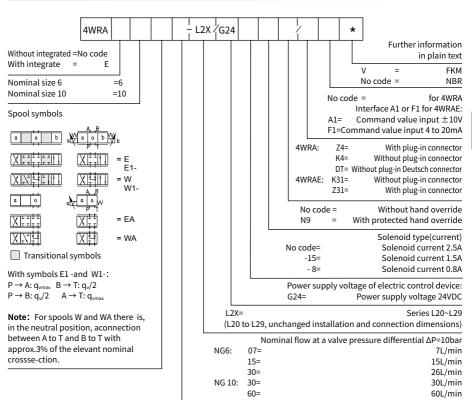
Type 4WRAE...-L2X/...



Type 4WRAE...A-L2X/...



Ordering code



Technical data

1. Hydraulic						
Installation		Optional, preferably horizontal				
Nominal size			6	10		
Weight	4WRAL2X	Kg	2.0	6.6		
	4WRAEL2X		2.2	6.8		
Nominal flow Q_{vnom} at $\Delta p = 10$ bar L/m		L/min	7,15,26	30,60		
Hysteresis %		%	≤ 5			
Reversal span		%	≤ 1			
Response sensitivity %		%	≤ 0.5			
Max.operating	Ports A, B, P	bar	315			
pressure	Port T	bar	210			
Pressure fluid			Mineral oil (HL, HLP) to DIN 51524			
Pressure iluiu		Other pressure fluids on request!				
Ambient air	4WRAL2X	°C	-20°C to 70°C (-4° F to 158° F)			
temperature range	4WRAEL2X	°C	-20°C to 50°C (-4° F to 122° F)			
Viscosity range mm²/s		20 to 380 (preferably 30 to 46)				
Fluid Cleanliness Class		NAS1638 class9 or ISO 4406 class 20/18/15				

2. Electrical								
1) Solenoid data								
Voltage type		DC	DC					
Command value signal for 4WRAE		±10V or 4	± 10 V or 4 \sim 20mA					
Max.current per solenoid		А	2.5	1.5	0.8			
Solenoid coil	Cold value at 20°C	Ω	2	4.8	19.5			
resistance	Max.warm value		3	7.2	28.8			
Duty		%	ED100%	ED100%				
Max.coil temperature		°C	150					
Valve protection to EN 60529		IP 65						
2) Control electronics								
Amplifier	4WRAL2X		VT-VSPA2L2X					
	4WRAEL2X		Integrated in the valve(OBE)					
	Nominal voltage	VDC	24					
Supply voltage	Lower limiting value	V	21/22(4WRA), 19(4WRAE)					
	Upper limiting value	V	35					
Amplifier power	I _{max}	А	<1.8	<1.8				
consumption	Impulse current	Α	3					

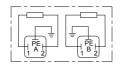
Electrical connections, plug-in connectors

nominal dimensions in mm

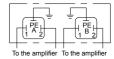
•For type 4WRE...L2X (without integrated electronics)

Connections on the component plug

Plug-in connector to DIN EN 175301-803 or ISO 4400



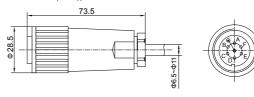
Connections on the plug-in connector



·For type 4WRAE...L2X (with integrated electronics (OBE))

For pin allocation also see block circuit diagram.

Plug-in connector to DIN EN 175201-804



· Integrated control electronics for type 4WRAE

Component plug allocation

		Contact	Interface A1 signal	Interface F1 signal	
	Supply	A 24 VDC(U(t)=1		=19V to 35V)	
	voltage	В	GND		
		С	n.	c. 1)	
Differential amplifier input	Differential	D	±10V, Re>50KΩ	4 to 20mA, Re>100Ω	
	E	reference potentional command value			
ĺ		F	n.c. 1)		

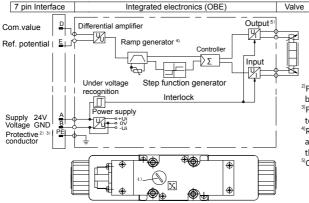
Connection cable:

Recommended: - up to 25 m cable length type LiYCY 7x0.75 mm² - up to 50 m cable length type LiYCY 7x1.0 mm². For outside diameter see plug-in connector sketch. Only connect screen to PE on the supply line.

A positive command value 0 to +10 V (or 12 to 20 mA) at D and the reference potential at E results in a flow from P to A and B to T. A negative command value 0 to -10 V (or 12 to 4 mA) at D and the reference potential at E results in a flow from P to B and A to T.

For a valve with 1 solenoid on side a (e.g. spool variants EA and WA) a positive command value at D and the reference potential at E results in a flow from P to B and A to T.

·Integrated electronics (OBE) for type 4WRAE...L2X



²⁾PE is connected to the cooling body and the valve housing! 3) Protective conductor screwed to the valve housing and cover. 4)Ramp can be externally adjusted from 0 to 2.5s, the same applies for Tup and Tdown. 5)Output stages current regulated.

¹⁾Contacts C and F must not be connected!

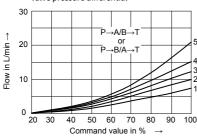
Characteristic curves

(measured with HLP46, ϑ_{oil} =40°C ±5°C)

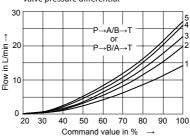
· Type 4WRAE (NG 6 and 10)

NG 6

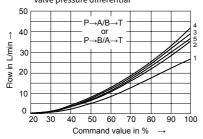
7 L/min nominal flow at a 10 bar valve pressure differential



15 L/min nominal flow at a 10 bar valve pressure differential



30 L/min nominal flow at a 10 bar valve pressure differential

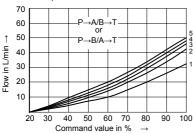


- 1 Δp=10bar constant
- 2 Δp=20bar constant
- 3 Δp=30bar constant
- 4 Δp=50bar constant
- 5 Δp=100bar constant

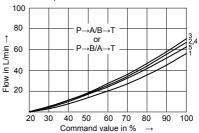
Δp=Valve pressure differential (inlet pressure po minus loadpressure p_Lminus return pressure p_T)

NG 10

30 L/min nominal flow at a 10 bar valve pressure differential 70



60 L/min nominal flow at a 10 bar valve pressure differential



- 1 ∆p=10bar constant
- 2 Δp=20bar constant
- 3 ∆p=30bar constant
- 4 Δp=50bar constant
- 5 Δp=100bar constant

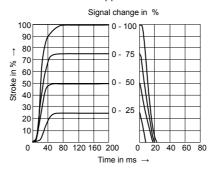
Δp=Valve pressure differential (inlet pressure p, minus load pressure p, minus return pressure p,

Characteristic curves

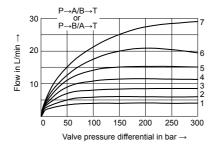
(measured with HLP46, ϑ_{oil} =40°C ±5°C)

NG 6

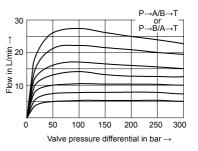
Transient function with a stepped form of electrical input sign

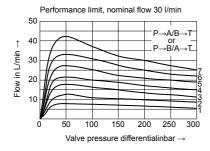


Performance limit, nominal flow 7 l/min



Performance limit, nominal flow 15 l/min





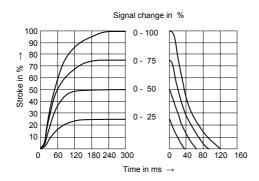
- 1.Com. value = 40 %
- 2.Com. value = 50 %
- 3.Com. value = 60 %
- 4.Com. value = 70 %
- 5.Com. value = 80 %
- 6.Com. value = 90 %
- 7.Com. value = 100 %

If the performance limits are exceeded then flow forces occur which lead to uncontrolled spool movements.

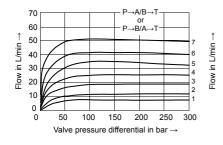
Characteristic curves

(measured with HLP46, ϑ_{oil} =40°C \pm 5°C)

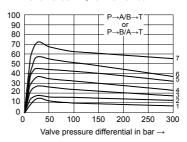
NG 10 Transient function with a stepped form of electrical input sign



Performance limit, nominal flow 30l/min



Performance limit, nominal flow 60 l/min



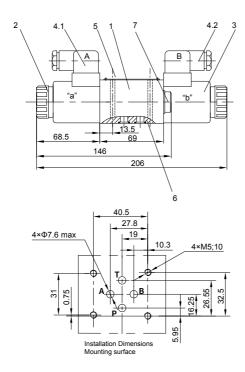
1.Com. value = 40 % 2.Com. value = 50 % 3.Com. value = 60 % 4.Com. value = 70 % 5.Com. value = 80 % 6.Com. value = 90 %

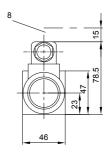
7.Com. value = 100 %

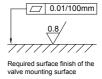
If the performance limits are exceeded then flow forces occur which lead to uncontrolled spool movements.

(nominal dimensions in mm)

Type 4WRA6...L2X







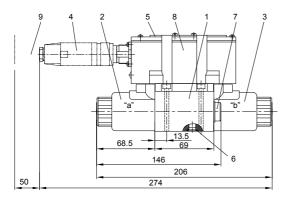
- Valve housing 1
- Proportional solenoid "a"
- Proportional solenoid "b"
- 4.1 Plug-in connector "A"
- 4.2 Plug-in connector "B"
- 5 Name plate
- 6 Identical seal rings for ports A, B, P and T $(R-ring 9.81 \times 1.5 \times 1.78 \text{ or } O-ring 9.25 \times 1.78)$
- 7 Plug for valves with one solenoid (2 switching positions, versions EA or WA)
- 8 Space required to remove the plug-in connector

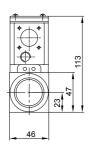
Valve mounting screws

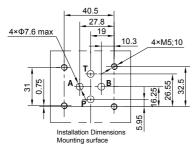
- 4 S.H.C.S.ISO 4762 M5 × 50 10.9
- -4GB/T70.1-M5×50-10.9
- Tightening torque M_A = 8.9 Nm \pm 10%

(nominal dimensions in mm)

Type 4WRAE6...L2X









Required surface finish of the valve mounting surface

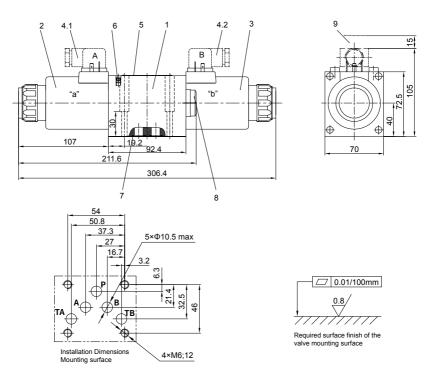
- 1 Valve housing
- 2 Proportional solenoid "a"
- 3 Proportional solenoid "b"
- 4 Plug-in connector
- 5 Name plate
- 6 Identical seal rings for ports A, B, P and T $(R-ring 9.81 \times 1.5 \times 1.78 \text{ or } O-ring 9.25 \times 1.78)$
- 7 Plug for valves with one solenoid (2 switching positions, versions EA or WA)
- 8 Integrated electronics (OBE)
- 9 Space required to remove the plug-in connector

Valve mounting screws

- 4 S.H.C.S.ISO 4762 M5×50 10.9
- -4 GB / T 70.1 M5×50 10.9
- Tightening torque $M_A = 8.9 \text{ Nm} \pm 10\%$

(nominal dimensions in mm)

Type 4WRA10...L2X



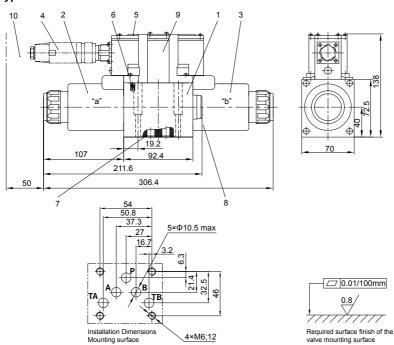
- 1 Valve housing
- Proportional solenoid "a" 2
- Proportional solenoid "b"
- 4.1 Plug-in connector "A"
- 4.2 Plug-in connector "B"
- 5 Name plate
- 6 Valve bleed screw
- 7 Identical seal rings for ports A, B, P and T (R-ring $13 \times 1.6 \times 2$ or O-ring 12×2)
- 8 Plug for valves with one solenoid (2 switching positions, versions EA or WA)
- Space required to remove the plug-in connector

Valve mounting screws

- 4 S.H.C.S.ISO 4762 M6×40 10.9
- 4 GB / T 70.1 M6×40 10.9
- Tightening torque $M_A = 15.5 \text{ Nm} \pm 10\%$

(nominal dimensions in mm)

Type 4WRAE10...L2X



- 1 Valve housing
- 2 Proportional solenoid "a"
- 3 Proportional solenoid "b"
- 4 Plug-in connector
- 5 Name plate
- 6 Valve bleed screw
- 7 Identical seal rings for ports A, B, P and T (R-ring $13 \times 1.6 \times 2$ or O-ring 12×2)
- 8 Plug for valves with one solenoid (2 switching positions, versions EA or WA)
- 9 Integrated electronics (OBE)
- 10 Space required to remove the plug-in connector

Valve mounting screws

- 4 S.H.C.S.ISO 4762 M6×40 10.9
- 4 GB / T 70.1 M6×40 10.9
- Tightening torque M_A = 15.5 Nm \pm 10%